Polarization Control Interface
Automatic or manual polarization control for three-wire Polarotor™ or optional control for 24V rotating feeds with potentiometer feedback

High-Resolution Pulse Sensor Interface
Ensures accurate Ku-band positioning

Software Controlled Limits
Provides backup to mechanical limits

Dual Speed
For fast slewing, fine positioning, user programmable

RS-422 PC Control Interface
Automated control with many popular packages; basic PC-control software is included

Adapti-Drive™
Maintains stable speed with varying load

Solid-State Drive Circuitry
Provides reliable, quiet operation, rated for 36V at 10A with over-current protection

Multi-Band Operation
Supports C, Ku and L-band satellites
**OPERATIONAL OVERVIEW**

The RC1500 was designed to provide years of reliable operation through the use of a heavy duty solid-state drive network coupled with a novel microcontroller-based fault monitoring system. The 10 amp rated drive output capability is adequate for either moving feed trackers or full-size linear actuators and the Adapti-Drive digital servo speed control optimizes antenna movement for today's demanding Ku-band applications. Additional features like an RS-422 communications port for PC control and a very user-friendly, menu scheme make the RC1500 a unique and highly adaptable piece of equipment. Overall, the RC1500 is well equipped to handle the demanding requirements for cost sensitive domestic and optionally international inclined-orbit satellite tracking.

**MODES**

The RC2000A operates in a mode architecture whereby the controller's operational status is governed by the selected mode. An explanation of these modes are listed below.

- **MANUAL:** Allows for manual jogging of the azimuth and polarization axis. The fast/slow speed toggle is active in this mode.
- **AUTO:** A satellite, previously saved in memory, can be recalled and the RC1500A will position the antenna on the selected satellite.
- **SETUP:** This mode stores values memory for a selected satellite.
- **RESET:** Used to reset the drive over-current protection circuits after the load error has been corrected.
- **DELETE:** Allows the user to delete a satellite from the list of stored values.
- **FIX:** Used to restore the proper position counters in the event of a memory error or sensor failure.
- **AZIM SLOW:** This mode allows the user to select an appropriate drive slow speed value to optimize system performance.
- **CONFIG:** Provides a concise point to enter any necessary system constants or enable options.
- **LIMITS:** Software limits are set for the main axis. This is used as a backup for mechanical limits.

**SPECIFICATIONS**

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<thead>
<tr>
<th>PHYSICAL</th>
<th>DRIVE</th>
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<tr>
<td>Size: 19.0” x 3.5” x 9.0” (rack)</td>
<td>Output: 36 VDC, 10.0 Amps; 360VA</td>
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<td>Weight: 8.5 lbs.</td>
<td>Sensor Input: Pulse-type: Reed, Hall Effect, Optical</td>
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<td>Temperature: 0° – 50° C</td>
<td>Polarization: Standard Polarotor™ Interface, optional rotating Feed-drive at voltages from 5 – 36 VDC @ 1A max</td>
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<td>Input Power: 115/230 VAC, 50/60 Hz., 40 W</td>
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